# \UTOM\TE<sub>™</sub>

### AX30/AX50 EXTERNAL SHADE MOTOR









ELECTRONIC LIMIT



FAVORITE POSITION



AUTOMATE RADIO COMMUNICATION



IMPACT DETECTION

 $AUTOMATE \mid AX30/AX50 \; External \; Shade \; Motor \; combine \; the \; simple, intuitive \; features \; of \; ARC \; "Automate \; Radio \; Communication" \; with \; the \; higher \; lifting \; capacity \; for \; larger \; shade \; applications.$ 

## CONTENTS

1	ASSEMBLY	5
2	WIRING	6
2.1	EU/AU Motor	6
2.2	US Motor	6
3	P1 BUTTON FUNCTIONS	7
3.1	Motor state test	7
3.2	Motor configuration options	7
4	MODES	8
4.1	Selectable modes	8
5	FOLDING ARM AWNING - OPEN SYSTEM	9
5.1.	Pair motor with controller	9
5.2	Check motor direction	10
5.3	Change motor direction	10
5.4	Set limits	11
6	FOLDING ARM AWNING - CASSETTE SYSTEM	12
6.1	Pair motor with controller	12
6.2	Check motor direction	13
6.3	Change motor direction	13
6.4	Select motor mode	14
6.5	Set limits	14
7	VERTICAL DROP MODE	15
7.1	Pair motor with controller	15
7.2	Check motor direction	16
7.3	Select motor mode	17
7.4	Set limits	17
7.5	Impact detection (only with Zipscreen)	18
7.6	Activate/Deactivate Impact Detection Mode	18
8	GENERAL INSTRUCTIONS	19
8.1	Adjust upper limit	19
8.2	Adjust lower limit	19
8.3	Delete upper/lower limits	20
8.4	Add controller and channel	20
8.4.1 contr	Using P2 button on existing controller to add a no coller or channel	ew 20
8.4.2 contr	Using a pre-existing controller to add or delete roller or channel	a 21
8.5	Favorite positioning	21
8.5.1	Set a favorite position	21

14	TROUBLE SHOOTING	24
8.8.1	Sensor prioritize function	23
8.8	Sensor function	23
8.7	Reset to factory settings via remote	23
8.6	Sleep mode	22
8.5.3	Delete favorite position	22
8.5.2	Send shade to favorite position	22

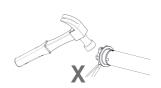
### **SAFETY INSTRUCTIONS**

### WARNING: Important safety instructions to be read before installation.

Incorrect installation can lead to serious injury and will void manufacturer's liability and warranty.

It is important for the safety of persons to follow the enclosed instructions. Save these instructions for future reference







- Do not expose to water, moisture, humid and damp environments or extreme temperatures
- Persons (including children) with reduced physical, sensory or mental capabilities, or lack of experience and knowledge should not be allowed to use this product.
- Keep away from children.
- Use or modification outside the scope of this instruction manual will void warranty.
- Installation and programming to be performed by a suitably qualified installer.
- For use with motorized shading devices.
- Ensure correct crown and drive adapters are used for the intended system.
- Keep antenna straight and clear from metal objects
- Do not cut the antenna.
- Follow Rollease Acmeda installation instructions.
- Before installation, remove any unnecessary cords and disable any equipment not needed for powered operation.
- Ensure torque and operating time is compatible with end application.
- Motor is to be installed in horizontal application only.
- The routing of cable through walls shall be protected by isolating bushes or grommets.
- Ensure power cable and aerial is clear and protected from moving parts.
- If cable or power connector is damaged do not use.
- Route motor cable to create a drip loop
- Frequently inspect for improper operation. Do not use if repair or adjustment is necessary.
- Keep motor away from acid and alkali.
- Do not force the motor drive
- Keep clear when in operation.

Rollease Acmeda declares this equipment is in compliance with the essential requirements and other relevant provisions of R&TT EC Directive 1999/5/EC

#### SAFETY INSTRUCTIONS

#### Statement Regarding FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

#### Note:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- •Consult the dealer or an experienced radio/TV technician for help.

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

#### Statement Regarding IC Compliance

- 1. This device complies with Industry Canada RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.
- 2. Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.
- -French:

Leprésent appareil est conforme aux CNR d'Industrie Canada applicable aux appareils radio

Exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

(1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, meme si le brouillage est susceptible d'en compromettre le fonctionnement."

CAN ICES-3 (B)/NMB-3(B)









### **ASSEMBLY**

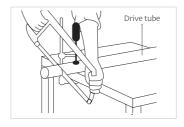
Please refer to Rollease Acmeda System Assembly Manual for full assembly instructions relevant to the hardware system being used, including recommended crown, drive and bracket adapter kits.

**Step 1.** Cut roller tube to required length.

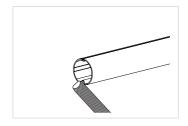


#### IMPORTANT

Impact detection does not require a 2 piece drive set. The use of a standard 1 part drive adapter is compatible. Zipscreen is needed to let the impact transmit to the top during downward movement. The top tube must be able to freely rotate  $\sim 5$  degrees after installation.

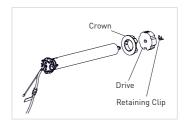


### **Step 2.** Ensure roller tube is clean and free from burrs.



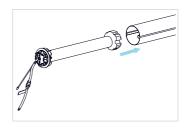
**Step 3.** Fit required crown, drive and bracket adapters.

Tube must be close fitting with chosen crown and drive adapters.

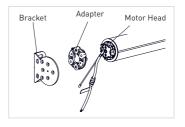


Step 4. Slide Motor into tube.

Insert by aligning key-way in crown and drive wheel into the tube.



Step 5. Mount motorized tube onto brackets.



### 2.1 EU/AU Motor

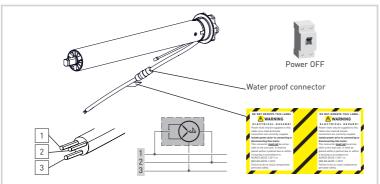
Disconnect the mains power supply.

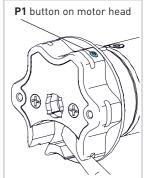
Connect the motor according to the information in the table below.



Ensure cable is kept clear of fabric.

Ensure antenna is kept straight and away from metal objects.





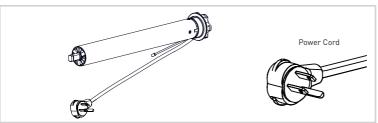
MOTOR	POWER	NEUTRAL	LIVE	EARTH	REGION
MT01-1145-069014	230V AC 50Hz	- Blue	Brown	Yellow/Green	EU
MT01-1145-069016					
MT01-1145-069013					A.I.I
MT01-1145-069015	240V AC 50Hz				AU

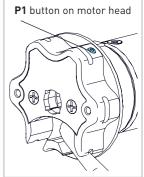
### 2.2 US Motor



Ensure cable is kept clear of fabric.

Ensure antenna is kept straight and away from metal objects.





MOTOR	POWER CORD LENGTH	POWER	NEUTRAL	LIVE	EARTH
MT01-1145-069017	240in. (6096mm)	120V AC 60Hz	White	Black	C
MT01-1145-069018	240111. (6076111111)	120V AC 60H2	vviiite	DIACK	Green

### 3 P1 BUTTON FUNCTIONS

### 3.1 Motor state test

This table describes the function of a short P1 Button press/release (<2 seconds) depending on current motor configuration.

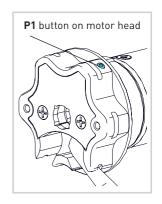
P1 Press	Condition	Function Achieved	Visual Feedback	Audible Feedback	Function Described
	If limit is NOT set	None	No Action	None	No Action
Short Press	If limits are set	Operational control of motor, run to limit. Stop if running	Motor Runs	None	Operational control of motor after pairing and limit setting is completed first time
	If motor is in "Sleep Mode" & limits are set	Wake and control	Motor wakes and runs in a direction	None	Motor is restored from Sleep Mode and RF control is active

### 3.2 Motor configuration options

The P1 Button is utilized to administer motor configurations as described below.

Hold **P1** button on motor head.

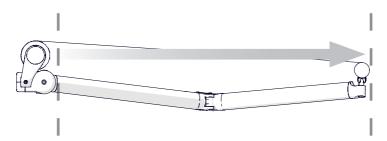




#### Selectable modes 4.1

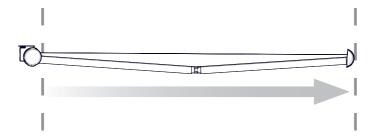
#### 1. FOLDING ARM AWNING - OPEN SYSTEM

Set Top and Bottom Limit Manually



#### 2. FOLDING ARM AWNING - CASSETTE SYSTEM

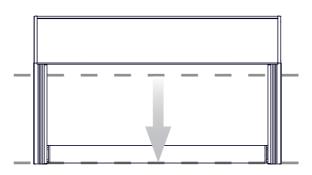
Set Bottom limit manually and Top limit is set automatically



#### 3. VERTICAL DROP

Set Top and Bottom Limit Manually

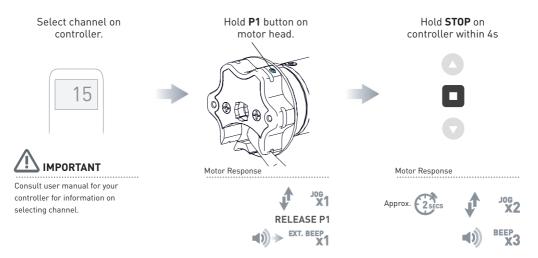
Impact Detection can be turned on - Refer to section for impact detection.



### 5 FOLDING ARM AWNING – OPEN SYSTEM

Note: For Cassette Mode and Vertical Drop Mode, refer to their respective sections.

### 5.1. Pair motor with controller





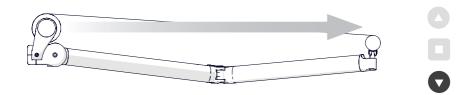
Motor is now in step mode and ready for setting limits

### 5.2 Check motor direction

Awning direction should be setup as below, so any paired sensors will activate correctly.

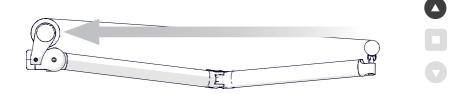
**DOWN** on the remote OPENS the Awning (awning moves in an outward direction).

E.g.



And **UP** on the remote CLOSES the Awning (awning moves in an inward direction).





### 5.3 Change motor direction

To check travel direction of shade, press **UP** or **DOWN** on controller.



Quick Press = Step
Long Press = Continuous Travel

To reverse shade direction, hold both  $\boldsymbol{\mathsf{UP}}$  and  $\boldsymbol{\mathsf{DOWN}}.$ 

Until the motor responds.



Motor Response











#### IMPORTANT

Damage to shade may occur when operating motor prior to setting limits. Attention should be given.

IMPORTANT

Reversing motor direction using this method is only possible during initial set-up

### 5.4 Set limits

Move shade to the desired highest or lowest position by pressing the **UP** or **DOWN** buttons on controller.







OR 🗀







#### IMPORTANT

Cycle shade up and down prior to setting limits to settle fabric

To save upper limit, hold **UP** and **STOP**.







To save lower limit, hold **DOWN** and **STOP**.







Motor Response











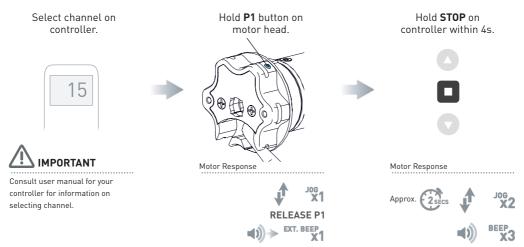
#### IMPORTANT

After setting limits, motor will automatically exit from initial set-up mode.

### 6 FOLDING ARM AWNING - CASSETTE SYSTEM

Note: For Non-Cassette Open Mode and Vertical Drop Mode, refer to section their respective sections.

### 6.1 Pair motor with controller





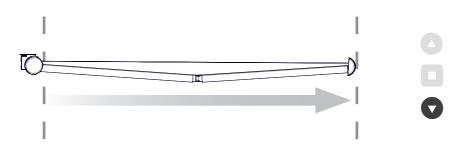
Motor is now in step mode and ready for setting limits

### 6.2 Check motor direction

Awning direction should be setup as below, so any paired sensors will activate correctly.

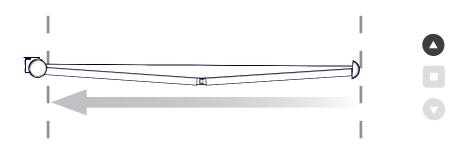
**DOWN** on the remote OPENS the Awning (awning moves in an outward direction).

E.g.



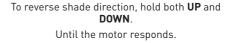
And **UP** on the remote CLOSES the Awning (awning moves in an inward direction).

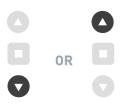
E.g.



### 6.3 Change motor direction

To check travel direction of shade, press **UP** or **DOWN** on controller.





Quick Press = Step Long Press = Continuous Travel



Motor Response

MPORTANT

Damage to shade may occur when operating motor prior to setting limits. Attention should be given.



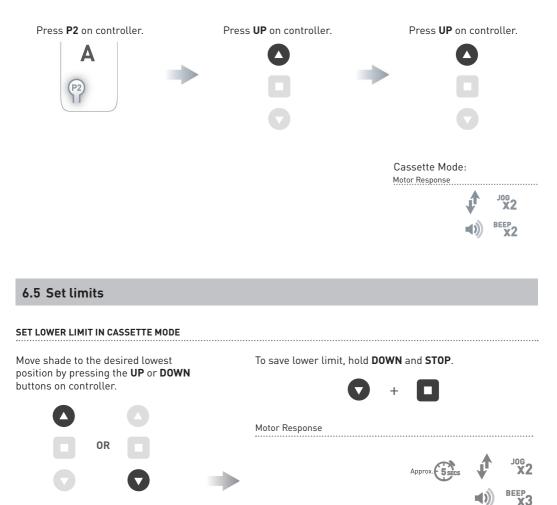




**IMPORTANT** 

### 6.4 Select motor mode

Now set the motor to cassette mode.



#### SET UPPER LIMIT IN CASSETTE MODE

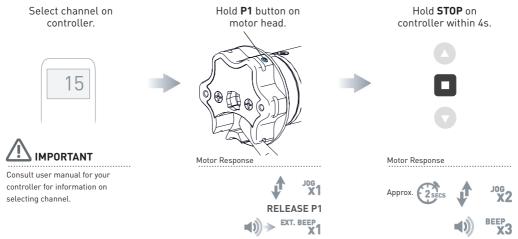
Press the **UP** button on the controller and the shade will retract until the terminal bar touches the cassette. The upper limit will automatically be set at this position.

### 7 VERTICAL DROP MODE

Note: For Non-Cassette Open Mode and Cassette Mode, refer to their respective sections.

### 7.1 Pair motor with controller

Note: Ensure Motor is in factory default setting.





Motor is now in step mode and ready for setting limits

### 7.2 Check motor direction

To check travel direction of shade, press **UP** or **DOWN** on controller.





Quick Press = Step Long Press = Continuous Travel To reverse shade direction, hold both **UP** and **DOWN**.

Until the motor responds.







Motor Response









Damage to shade may occur when operating motor prior to setting limits. Attention should be given.



### ! IMPORTANT

Reversing motor direction using this method is only possible during initial set-up

### 7.3 Select motor mode

Now set vertical drop mode.



Perform sequence **2** Times - Motor will Jog/Beep at the end of each sequence.

### Vertical Drop Mode:

Motor Response at the end of x2 sequence



### 7.4 Set limits

To save upper limit, hold **UP** and **STOP**.







Move shade to the desired highest or lowest position by pressing the **UP** or **DOWN** buttons on controller.















To save lower limit, hold **DOWN** and **STOP**.





















IMPORTANT

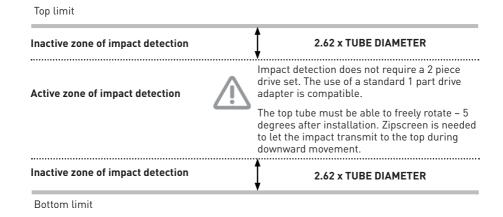
After setting limits, motor will automatically exit from initial set-up mode.



Cycle shade up and down prior to setting limits to settle fabric

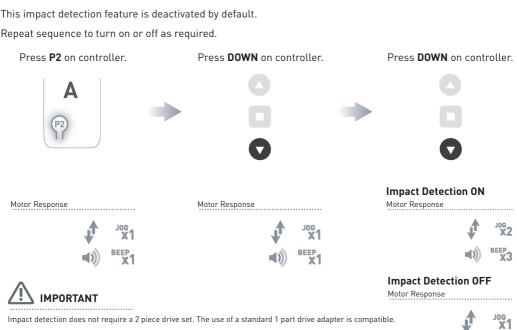
#### Impact detection (only with Zipscreen) 7.5

Impact detection is deactivated by default. If an obstacle is detected twice in the shade path during downwards movement, the motor lifts the shade up ~ 7.87in. (20cm).



#### **Activate/Deactivate Impact Detection Mode** 7.6

The Impact Detection feature only works in the active zone during downward movement.



transmit to the top during downward movement.

The top tube must be able to freely rotate ~ 5 degrees after installation. Zipscreen is needed to let the impact

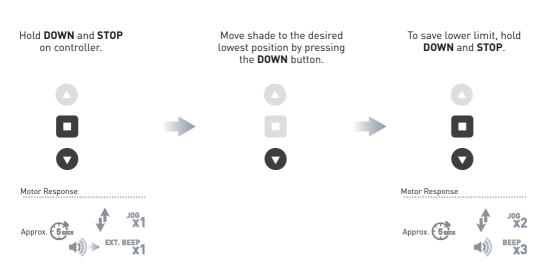
BEEF

### **8 GENERAL INSTRUCTIONS**

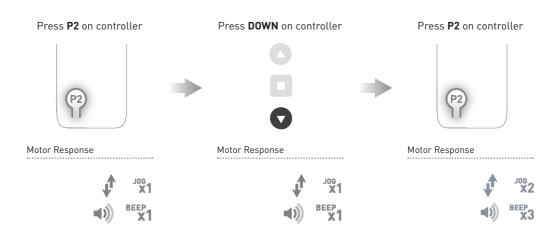
### 8.1 Adjust upper limit



### 8.2 Adjust lower limit



### 8.3 Delete upper/lower limits

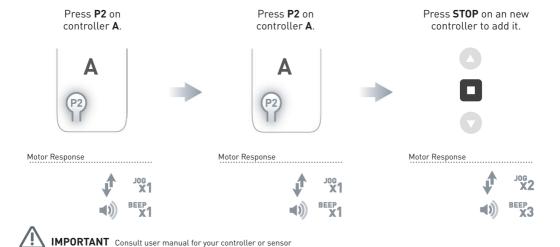


### 8.4 Add controller and channel

### 8.4.1 Using P2 button on existing controller to add a new controller or channel

**A** = Existing controller or channel (to keep)

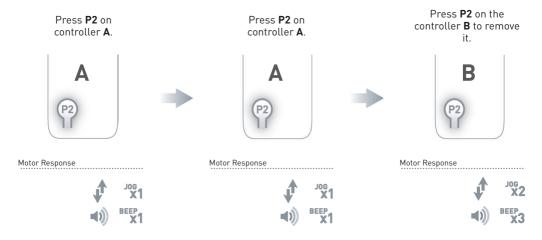
**B** = Controller or channel to add or remove



### 8.4.2 Using a pre-existing controller to add or delete a controller or channel

A = Existing controller or channel (to keep)

**B** = Controller or channel to add or remove



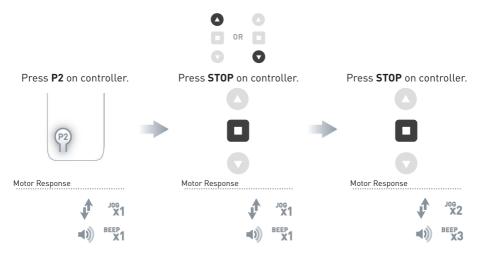


IMPORTANT Consult user manual for your controller or sensor

### 8.5 Favorite positioning

### 8.5.1 Set a favorite position

Move shade to the desired position by pressing the  ${\bf UP}$  or  ${\bf DOWN}$  button on the controller.



### 8.5.2 Send shade to favorite position



### 8.5.3 Delete favorite position



### 8.6 Sleep mode

If multiple motors are grouped on a single channel, Sleep Mode may be used to put all but 1 motor to sleep, allowing programming of just the one motor that remains "Awake".

#### **Enter Sleep Mode**

Sleep mode is utilized to prevent a motor from incorrect configuration during other motor setup.

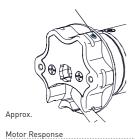
### Exit Sleep Mode: Method 1

Exit sleep mode once the shade is ready.

#### Exit Sleep Mode: Method 2

Remove power and then re-power the motor.

Hold P1 button on motor head.

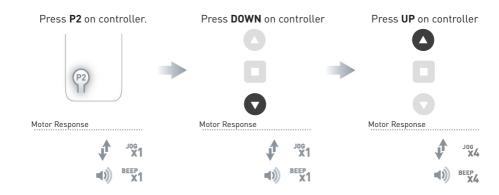


RELEASE P1

Press and release **P1** button on the motor head



### 8.7 Reset to factory settings via remote



### 8.8 Sensor function

### 8.8.1 Sensor prioritize function

Once the motor receives a command from the AUTOMATE solar wind and rain sensor or AUTOMATE motion sensor the motor will respond accordingly. At this point the motor will ignore any other remote or sensor commands for 8 minutes. This function is needed to avoid contradicting multiple triggers. Keep this in mind when testing the motor with the remote after the wind & rain sensor or motion sensor has been triggered. The sensor function is ON by default.

Note: Motor will jog to alert user if operated within the 8 minutes.

### 14 TROUBLE SHOOTING

Problem	Cause	Remedy	
	A/C power supply not plugged in.	Check motor to power cable connection and AC plug	
	Transmitter battery is discharged	Replace battery	
Matania ast mana dia a	Radio interference/shielding	Ensure transmitter is positioned away from metal objects and the aerial on motor or receiver is kept straight and away from metal	
Motor is not responding	Receiver distance is to far from transmitter	Move transmitter to a closer position	
	Power failure	Check power supply to motor is connected and active	
	Incorrect wiring	Check that wiring is connected correctly (refer to motor installation instructions)	
		Always reserve an individual channel for programming function	
Cannot program a single Motor (multiple motors respond)	Multiple motors are paired to the same channel	SYSTEM BEST PRACTICE - Provide an extra 15 channel controller in your multi-motor projects, that provides individual control for each motor for programming purposes	
		Place all other motors into sleep mode (refer to <b>P1</b> button function overview)	

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